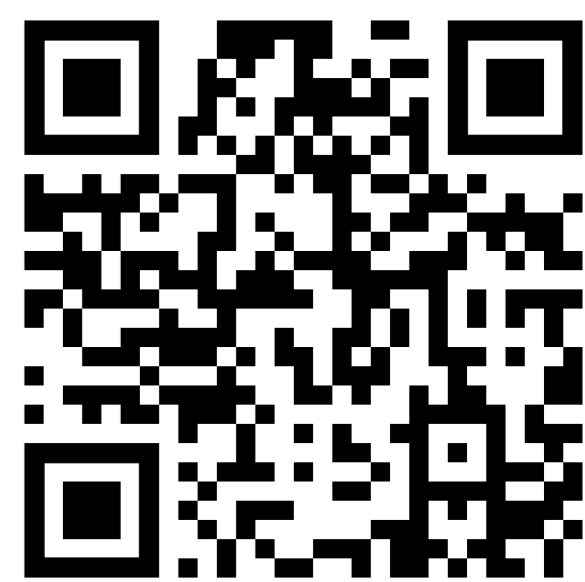


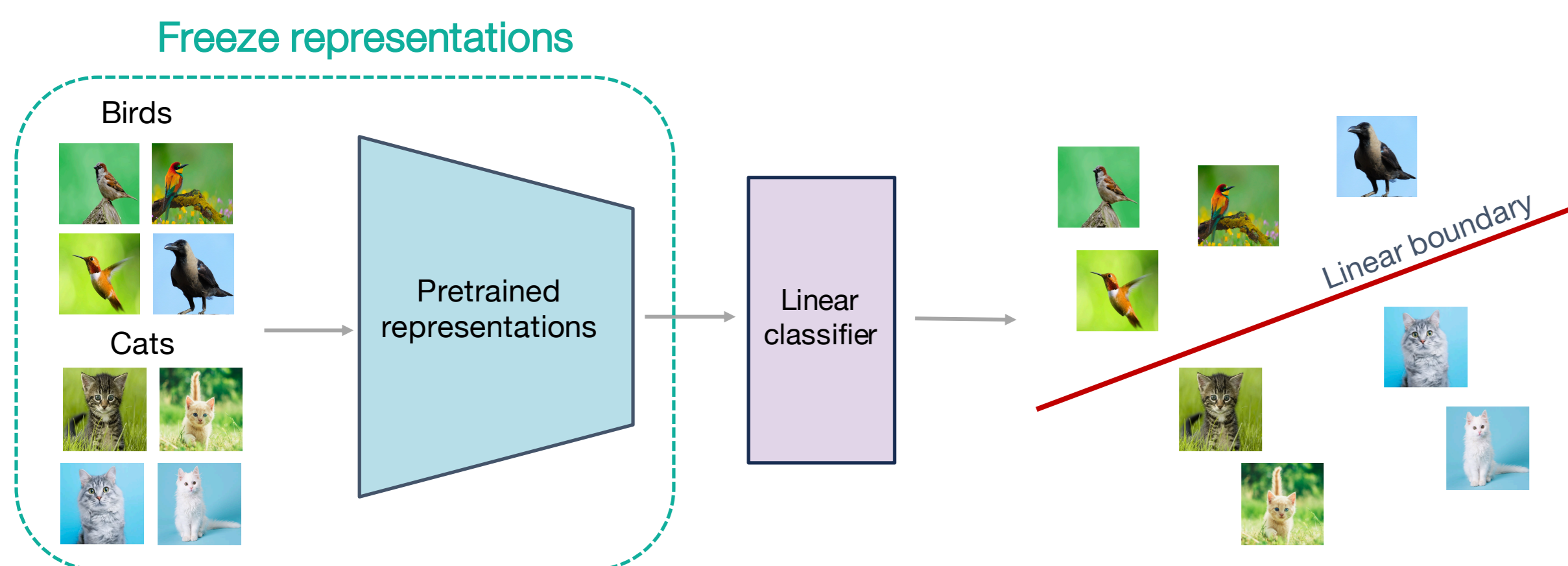
The Pursuit of Human Labeling: A New Perspective on Unsupervised Learning



Artyom Gadetsky and Maria Brbić

Motivation

Given pretrained representations, **supervised fine-tuning** is a standard approach to perform transfer learning to solve a new task

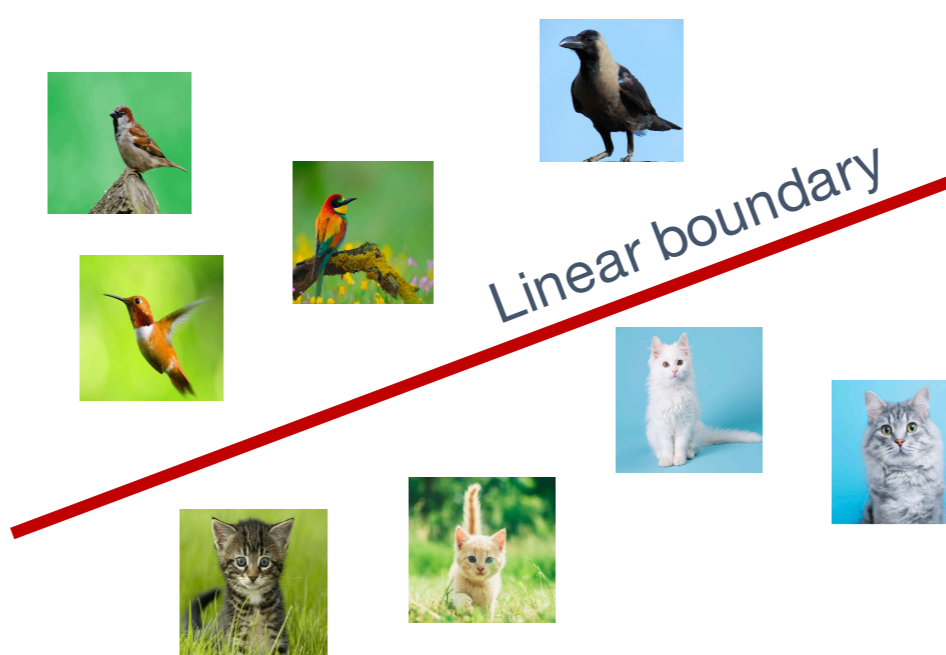


Can we use this paradigm for **unsupervised inference** of human labeled tasks?

What makes human labeled tasks special?

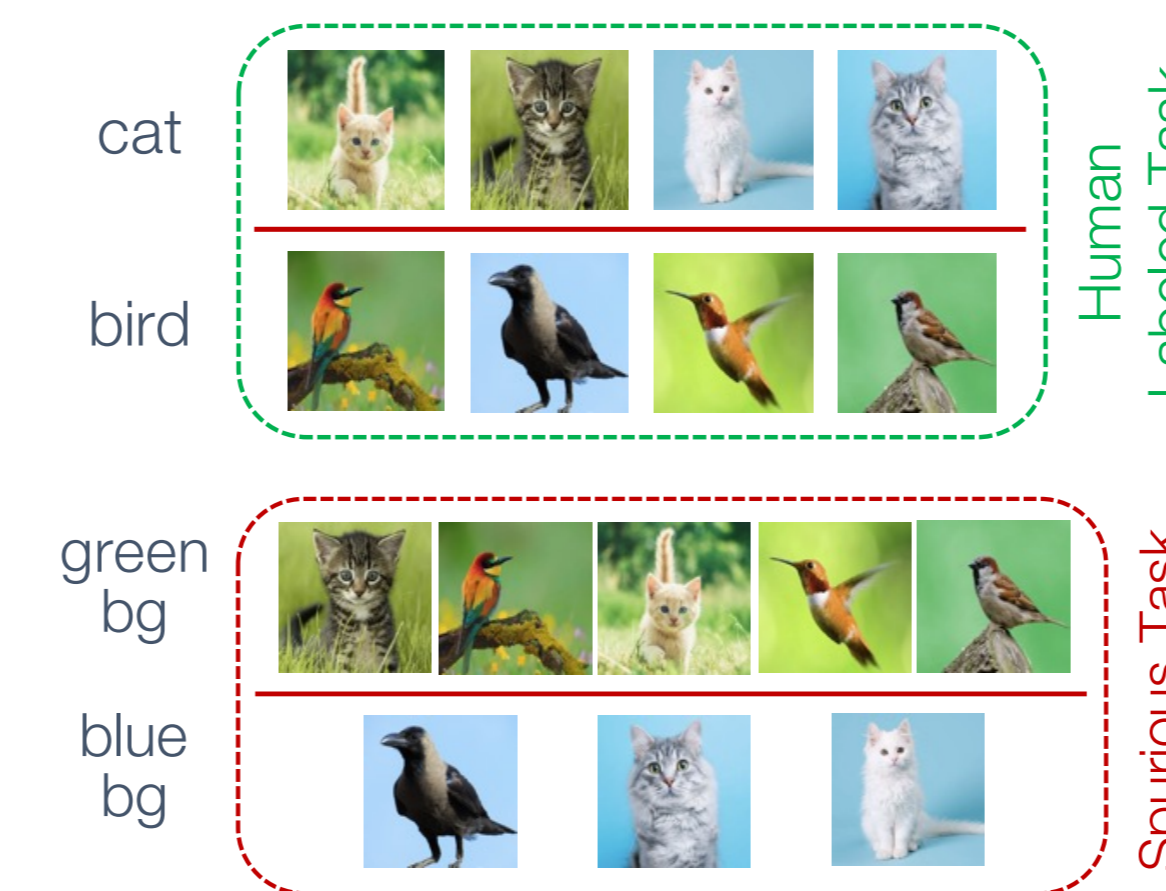
Observation 1:

Many human labeled tasks are **linearly separable** in a sufficiently strong representation spaces

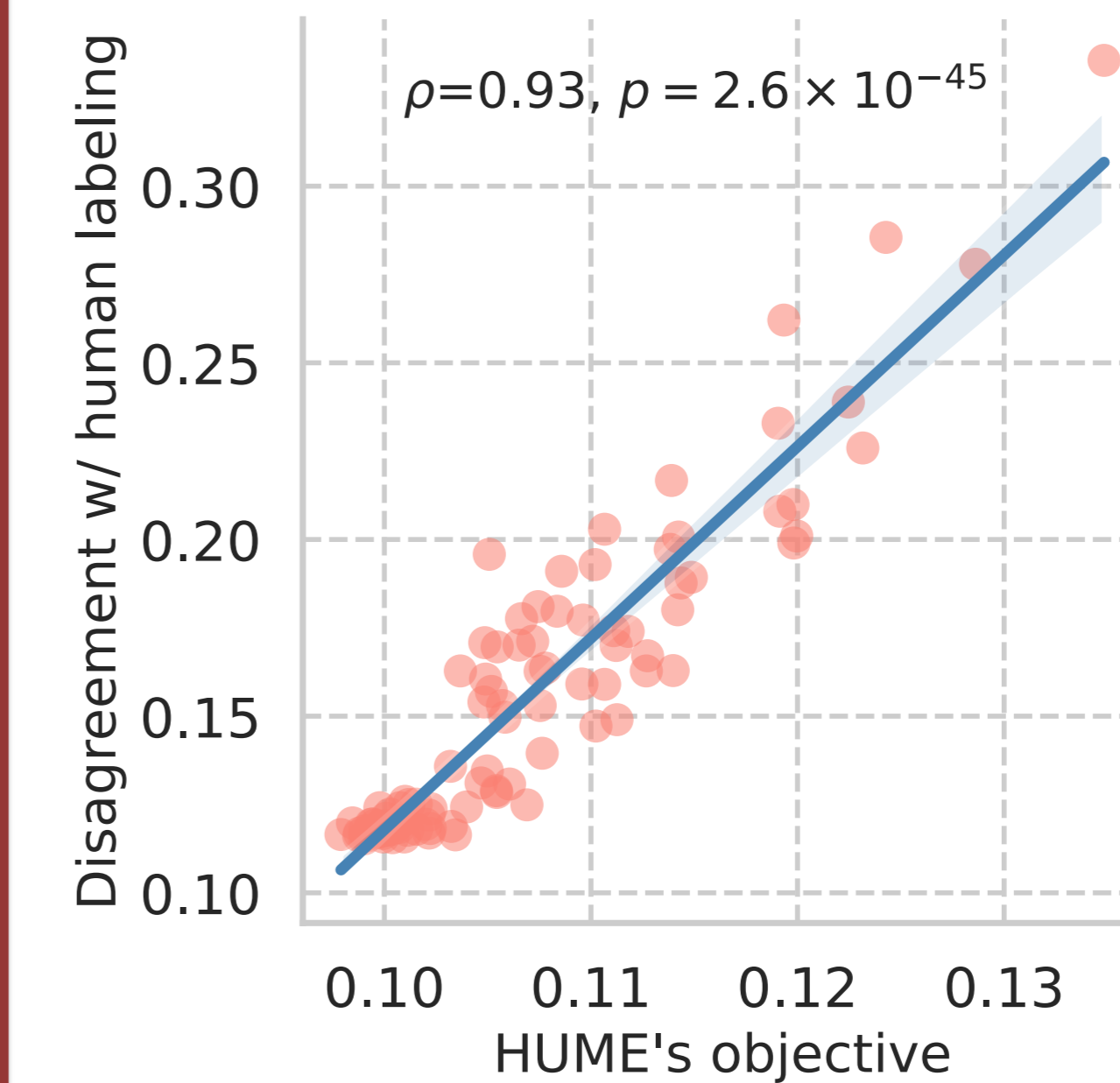


Observation 2:

Although each representation space has **its own inductive biases**, human labeled tasks are **invariant** to the underlying representation space



Results

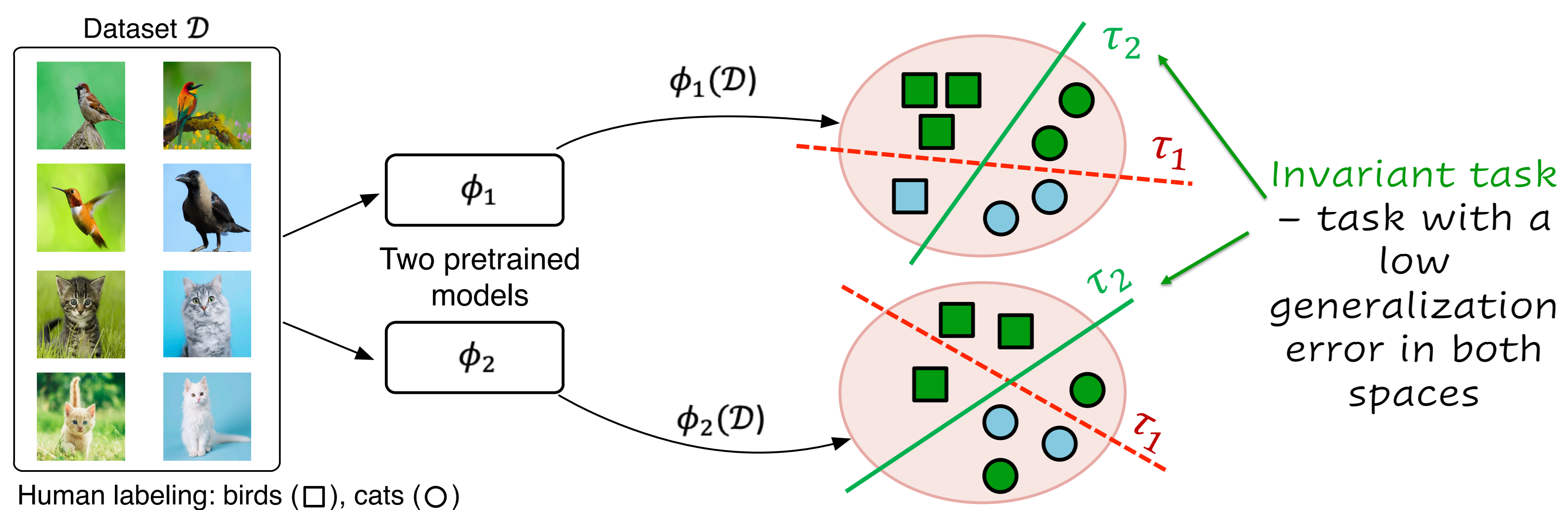


HUME's objective: Generalization error of linear classifiers in different representation spaces

Agreement with human labeling: HUME's objective is **lower** for the tasks that **better agree** with ground truth human labeled task

HUME trains **only** linear classifiers on top of pretrained models!

Our approach: HUME



Key idea behind HUME: Search for the task which attains the **lowest generalization error** in both representation spaces

Combinatorial optimization problem! How to solve it in practice?

Comparison to supervised fine-tuning: HUME can match the performance of the **supervised model** while being fully-unsupervised!

Method	STL-10		CIFAR-10		CIFAR-100-20	
	ACC	ARI	ACC	ARI	ACC	ARI
Supervised FT	88.9	77.7	89.5	79.0	72.5	52.6
HUME (Trans.)	93.2	86.0	89.2	79.2	56.7	39.6

Comparison to unsupervised baselines: HUME **outperforms** existing unsupervised baselines by a large margin!

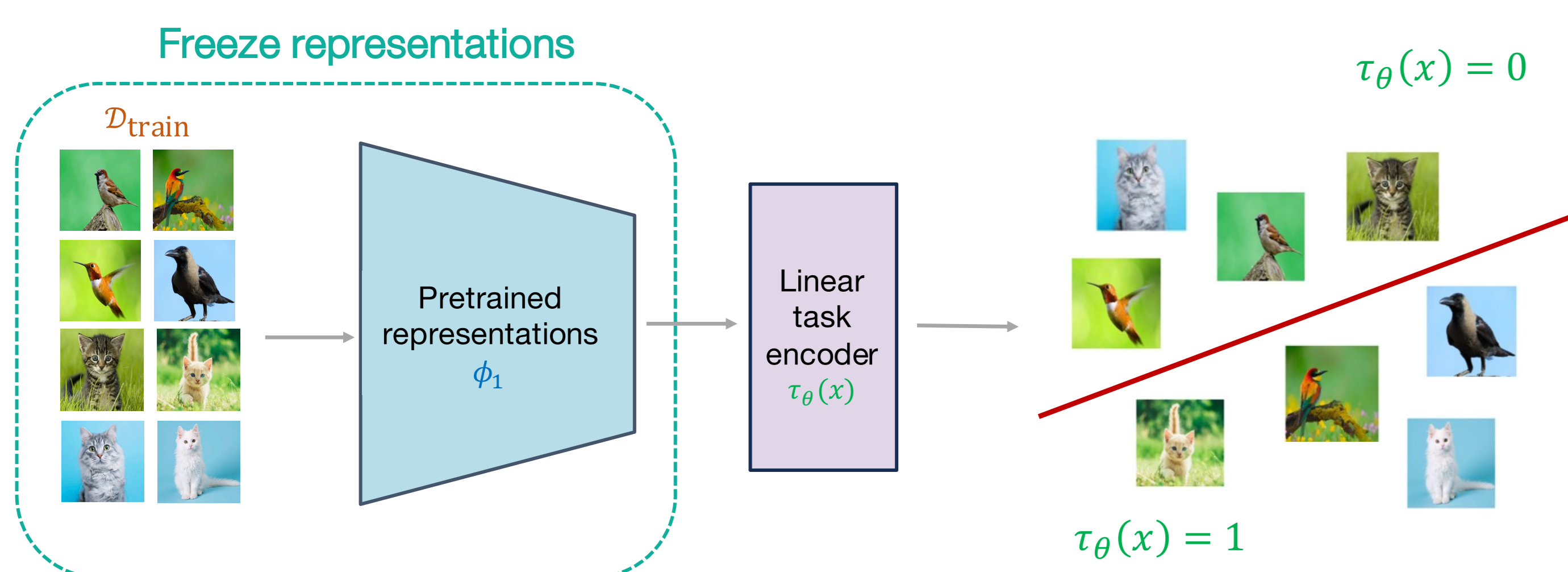
Method	STL-10		CIFAR-10		CIFAR-100-20	
	ACC	ARI	ACC	ARI	ACC	ARI
SCAN	77.8	61.3	83.3	70.5	45.4	29.7
SPICE	86.2	73.2	84.5	70.9	46.8	32.1
HUME (Ind.)	90.8	81.2	88.4	77.6	55.5	37.7

Large-scale unsupervised learning on the ImageNet-1k:

Method	ACC	ARI
SCAN	39.7	27.9
Twist	40.6	30.0
Self-classifier	41.1	29.5
HUME (Ind.)	51.1	38.1

HUME **scales** to large datasets and achieves **remarkable improvement** over existing baselines

Step 1: Label training split \mathcal{D}_{train} using a linear task encoder in the first representation space ϕ_1 .



Step 2: Fit generated labeling on the training split \mathcal{D}_{train} with a linear model in the second representation space ϕ_2 :

$$m^*(x) = \arg \min_{m(x); \tau_\theta(x)} \mathcal{L}_{\mathcal{D}_{train}}(m(x); \tau_\theta(x))$$

Step 3: Minimize generalization error of $m^*(x)$ with respect to a labeling τ_θ on a held-out \mathcal{D}_{test} :

$$\min_{\tau_\theta} \mathcal{L}_{\mathcal{D}_{test}}(m^*(x); \tau_\theta(x))$$